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1.5.2 ON

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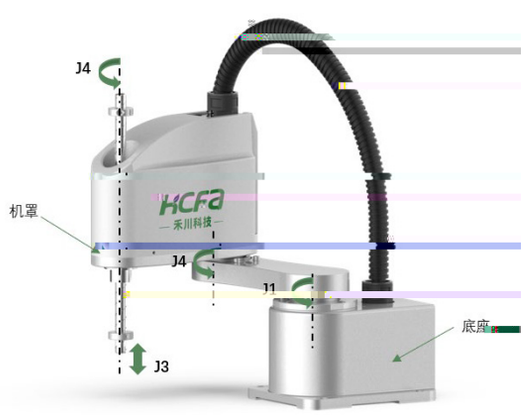
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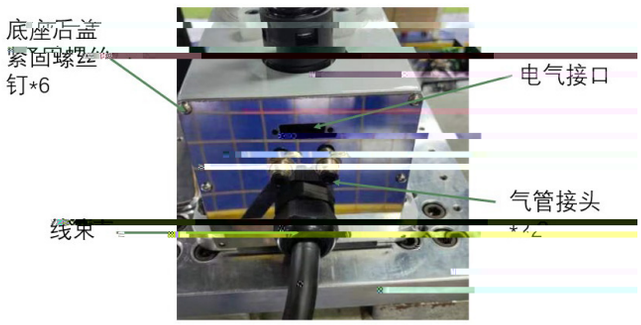
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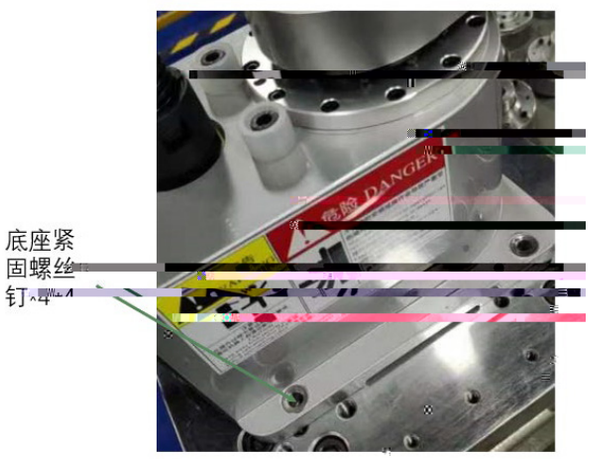
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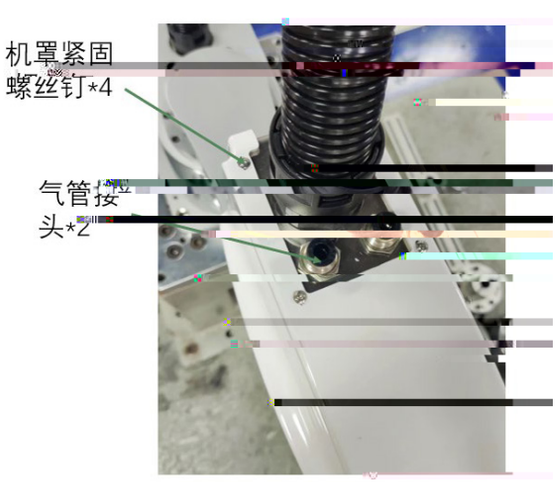
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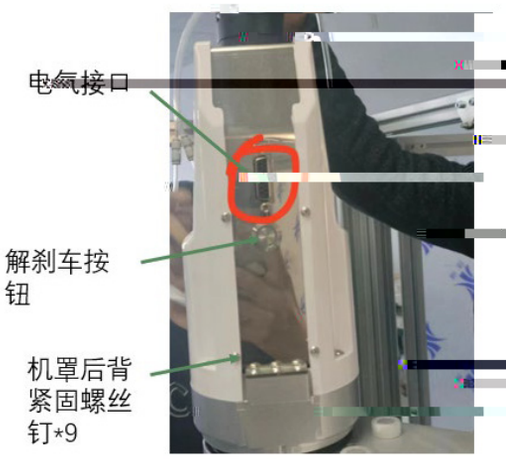


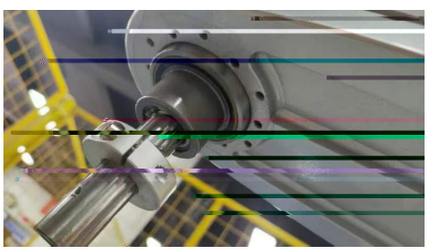
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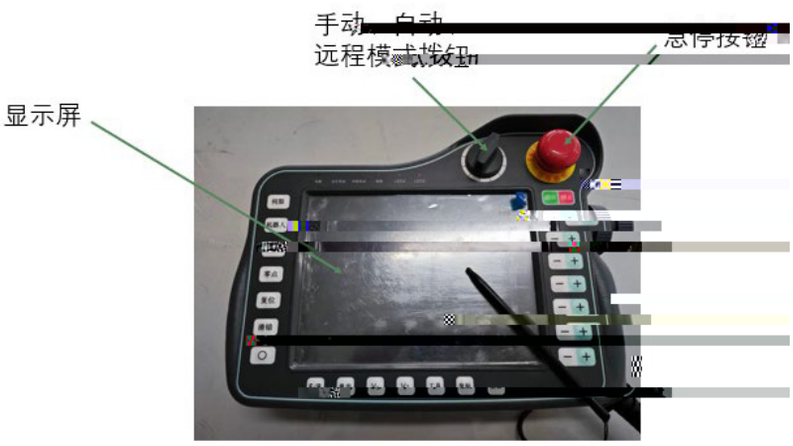

底座后盖
紧固螺丝
钉*6
电气接口
气管接头
*2
线束

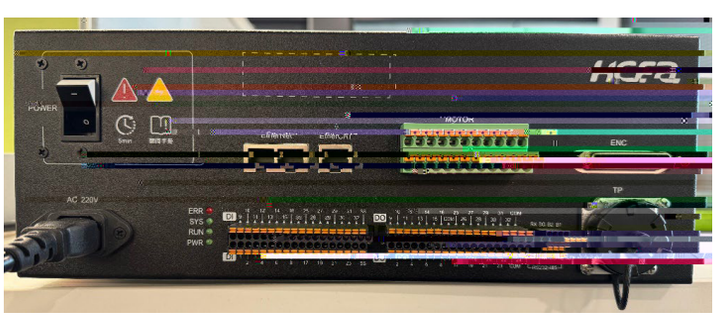

底座紧
固螺丝
钉*4


机罩紧固
螺丝钉*4
气管接
头*2


电气接口
解刹车按钮
机罩后背紧固螺丝钉*9




手动、自动、远程模式拨钮
急停按键
显示屏


POWER
AC 220V
ENC
TP
ERR
SYS
RUN
PWR

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1.6.1

1.6.2

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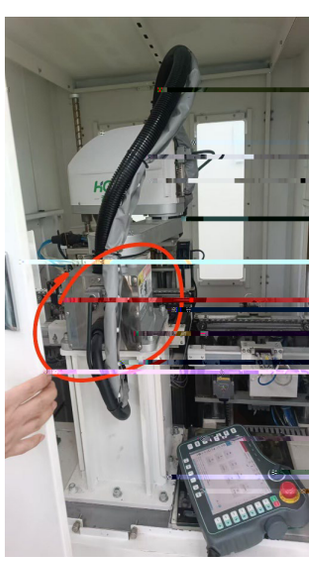
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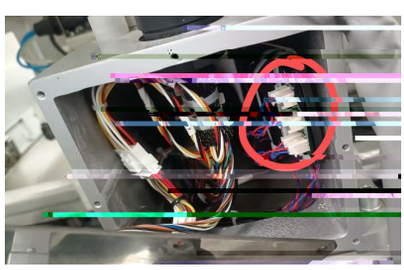
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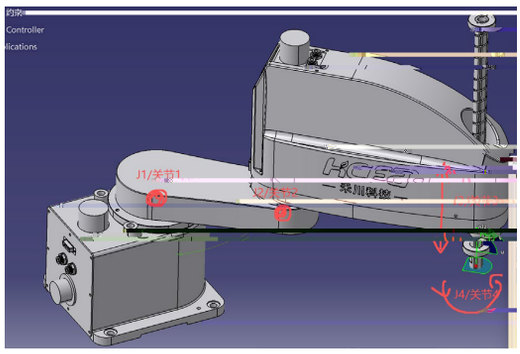




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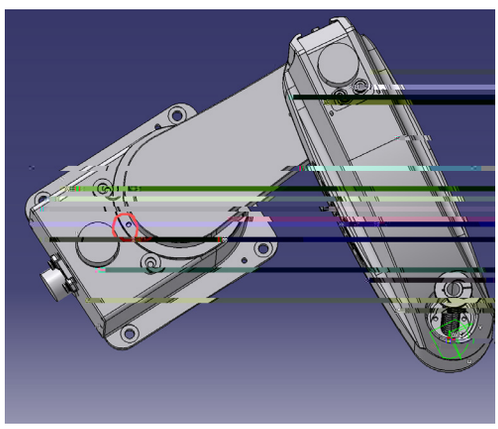
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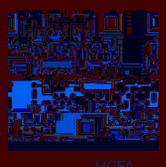

就绪
关节坐标系
工具0
用户0
负载0
前进
1%
SYR006
传送带压入
00:00:00.000
零点与Home点
零点
程序
应用
变量
I/O
机器人
监视
示教
设置
关节
外轴
基座轴
标记位（度或毫米）
外轴1
关节1
关节2
关节3
关节4
0
J1
J2
J3
J4
1
2
3
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5
6
7
8
9
确定
取消
全选
05-11 10:42:27.556 管理员已登录
05-11 10:42:31.358 操作员已登录
05-11 10:42:40.974 管理员已登录
05-11 10:42:50.369 操作员已登录



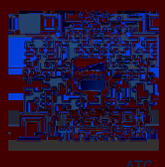
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